Digital Controller MAC6A/MAP6A Instruction manual



Thank you for purchasing SHIMAX products. Please check that the delivered Item is the item you ordered. Read this instruction manual thoroughly and understand its contents before using this product.

Please ensure that this manual is given to the final user of this product.



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Contents

1. Preface

This instruction manual is intended for those who will be involved in wiring, installation, operation and routine maintenance of the MAC6 and MAP6.

This manual describes the care, installation, wiring, function, and proper procedures regarding the operation of MAC6 and MAP6.

Keep this manual on hand while using this device. Please follow the provided guidance.

2. Matters regarding safety

This mark indicates hazardous conditions that could cause damage to equipment and/or facilities. Exercise extreme caution as indicated.

WARNING

This mark indicates hazardous conditions that could cause injury or death of personnel. Exercise extreme caution as indicated.

This mark indicates hazardous conditions that could cause damage to equipment and/or facilities. Exercise extreme caution as indicated.

″NOTE″

This mark indicates additional instructions and/or notes.

MAP6 is designed for controlling temperature, humidity, and other physical subjects in general industrial facilities. It must not be used in any way that may adversely affect safety, health, or working conditions.

To avoid damage to the connected equipment, facilities or the product itself due to a fault of this instrument, safety countermeasures must be taken before usage, such as proper installation of the fuse and the overheating protection device. No warranty, expressed or implied, is valid in the case of usage without having implemented proper safety countermeasures.

• The $\underline{\Lambda}$ mark on the plate affixed to the instrument on the terminal nameplate affixed to the case of your instrument, the $\underline{\Lambda}$ mark is printed. This is to warn you of the risk of electrical shock which may result if the charger is touched while it is energized.

• The external power circuit connected to the power terminal of this instrument must have a means of turning off the power, such as a switch or breaker. Install the switch or breaker adjacent to the instrument in a position which allows it to be operated with ease, and with an indication that it is a means of turning off the power. Use a switch or breaker, which meets the requirements of IEC127.

Fuse

Since the instrument does not have a built-in fuse, do not forget to install a fuse in the power circuit to be connected to the power terminal. The fuse should be positioned between the switch or breaker and the instrument and should be attached to the L side of the power terminal.

Fuse Rating: 250V AC 0.5A medium lagged or lagged type.

Use a fuse which meets the requirements of IEC127.

• Load voltage/current to be connected to the output terminal and the alarm terminal should be within the rated range. Otherwise, the temperature will rise and shorten the life of the product and/or result in problems with the product.

•Voltage/current that differs from input specification should not be connected to the input terminal. It may shorten the life of the product and/or result in problems with the product.

●Input, DI, AI, CT, and FB terminals are not insulated. When use a grounding-type sensor, please do not ground with those terminals.

●A signal wire's common mode voltage to ground (signal wires other than contact output including power supply and event) should be less than 30V rms, 42.4V peak, and 60 VDC.

● All the wires for the interior distribution, except for communication and contact output (including power supply and event), should be less than 30m in length. When the wire's length is 30m or more, or in the case of outdoor wiring, the suitable measure against a lightning surge is required.

EMC standard (IEC61326) classifies MAP6 into Class A apparatus. Electromagnetic interference may occur when MAP6 is used at a business district or in the home. Please use after taking sufficient measures.
There is a ventilation hole for radiation. Please make sure that the metal won't enter from this hole. It may be occur abreakdown and fire.

Do not block the draft hole or allow dust or the like to stick to it. A rise in temperature or insulation failure may result in a reduction of the life of the product and/or problems with it or may cause a fire.
It should be noted that repeated tolerance tests against voltage, noise, surge, etc. may lead to deterioration of the instrument.

•Users are prohibited from remodeling the product or abnormal use thereof.

3. Introductions

3-1. Check before use

Before using MAP6, please check the model code, the exterior appearance and accessories. Also make sure that there are no errors, impairs and shortages.

Confirmation of model code

Check that the product you ordered is being delivered properly. Check the model code of the main body case against the following code table.

Check of accessories

NOTE : Please contact our agencies or business offices if you have any problem. We welcome any kind of inquiry such as defect of the product, shortage of accessory and so on.

Handling Instruction

• Do not operate the keys on the front panel with a hard or sharply pointed object. Operate the keys only by softly touching them with fingertips.

• When cleaning the instrument, wipe it softly with a dry cloth. Never use solvents such as thinner.

3-2. Order code table

Item	Code	Sp	Specifications												
Series	MAP6A-	96	96 x 96 size 5 digit display programmable digital controller												
Series	MAC6A-	96 x 96 size 5 digit display digital controller													
Input		М	M Full multi TC, RTD, mV, V, mA ※1												
			С	Cont	ntact 1a 240V AC 2A (Resistance load)										
			S	Volta	age	pulse	(SSF	R Dri	ve Vo	ltage) 12V	DC	max20mA		
Control Output 1			I	Curr	ent	4-2	0mA	DC	E Lo	ad re	sista	nce	max500Ω		
			V	Volta	age	0-1	0V	DC	Lo	ad cu	irrent	ma	ax2mA	1	
			Y	Cont	rol	motor	(Sei	vo c	ontro	Out	put)C	Conta	act 1C 240V AC 2A	% 2	
			Х	Cont	Control motor (Servo control Output)SSR240V AC 2A										
Power sup	oply			F-	90	-264V	AC	50/	60Hz						
Event Ou	tput				Е	Even	Outp	out 3	3 poin	ts (E	V1-3) Co	ontact 1a 240V AC 1A	(Resistance load)	
						N-	No	ne							
	-					C-	Co	ntact	: 1a	240	V AC) 2A	(Resistance Load)	-	
Control O	utput 2					S-	Vol	tage	pulse	12V	DC	max	<20mA	-	
						I-	Cu	rent	4-2	20mA		max	<u>(500Ω</u>	※ 2	
						V-	Vol	tage	0-	1 100	<u>JC m</u>	$\frac{1}{2}$		-	
Event Ou ⁻	tput					E-	Eve (Re	ent o esista	utput ance	Ipo load)	int (I	EV4)	240V AC 2A		
DI (Exter	nal operat	ion i	nput))			D	7 P	oints	(DI1	–7) 5V DC 0.5mA				
					т	١		Ν	Nor	e					
D0-1(E	xternal op	erat	ion o	utput	1)		J	3 P	oints	s(DO1-3) 24V DC 20mA				
DO-Π(F	vternal on	orat	ion o	utout	π)			Ν	Non	е				
	ent sensor	inni	.ion 0 .it)	սպու	ш.	/			J	DO-	- 🛛 3	8 Poir	nts (DO4-6) 24V DC 20	0mA	
FB(Feed	pack input	:)	,						Н	CT	2 Poi	nts	50.0A		
(<i>,</i>							Ρ	FB	potentiometer input 3 wire $100 \Omega \sim 2 \mathrm{k}\Omega$				
										Ν					
A1/E										I	Current 4-20mA DC				
AI(Extern	iai analogu	ein	out)								(Reception resistance 100Ω)				
										V	(Innu	Voltage U-10V DC			
												Current 4-20mA DC			
AO(External analogue output)							Т	T Load resistance max3000							
						V	Voltage 0–10V DC max2mA								
												Ν	None		
Commun	ication											R	RS-485		
												W	RS-232C		

 $\triangle 1$ When using by current input, shunt resistance of option parts or same as items (less than 0.05% of 100 Ω) is needed.

1 When Motor control Y or X installed, Out2 and EV4 cannot install.

4. Installation and Wiring

4-1. Installation (Environmental conditions)

This instrument should not be used in any of the places mentioned below. Selection of these places may result in trouble with the instrument, damage to it or even a fire.

•Where flammable gas, corrosive gas, oil mist and particles generated.

• Where the temperature is below -10° C or above 50° C.

•Where the relative humidity is above 90% RH or below the dew point.

•Where highly intense vibration or impact is generated or transferred.

•Near high voltage power lines or where inductive interference can affect the operation of the instrument.

•Where undergo influence of the equipment which generates a high frequency.

•Where the instrument is exposed to dew drops or direct sunlight.

•Where the height more than 2000m.

Note

The environmental conditions belong to the installation category II of IEC664 and the degree of pollution is II.

4-2. Mounting

• Cut a hole for mounting the controller in the panel by referring to the cutout drawing.

The panel thickness should be 1.2 to 3.2 mm. (It can be mounted up to 20mm of thickness using attachment)

●MAP6 has pawls of fixing, just press it from the front of the panel.

Note

MAP6 is designed to be mounted on a panel. Do not use it without mounting on the panel.

4-3. External Dimensions and Panel Cutout



External dimension (Unit: mm)



Panel cutout (Unit: mm)



Note:

Proximity attachment by a single hole is possible only in the case of horizontal direction. When an apparatus that was attached in vertical direction is removed, a dedicated detachment tool is required.

When wiring, make sure to disconnect the power supply. Otherwise an electric shock may result.
 After wiring, do not touch terminals or other charged elements while it is energized. Otherwise an electric shock may result.

• After wiring, make sure the wiring are correct.

•Make sure that wiring operation is properly done in line with a terminal wire diagram.

● The press-fit terminal must fit an M3.0 screw and have a width of 6 mm or smaller. (Clamp receiving torque: 0.5 to 0.6Nm)

●For wiring for power supply, use a 600V vinyl insulated wire or cable which is 1mm² or larger in section or a wire or cable of equivalent for higher performance.

•For Thermocouple input use compensation wire compatible with the type of thermocouple.

• For RTD input the resistance of single lead wire have to be 10Ω or less, and the three wire have to have same resistance.

• The input signal wire must not be accommodated with a high-voltage power cable in the same wiring conduit or duct.

Shielded wire (one-point grounding) is effective to avoid electrostatic induction noise.

•Twisting the input wires at short and equal intervals is an effective way to avoid magnetic induction noise.

4-5. Terminal arrangement



Note: If input type is thermocouple or voltage, errors may occur when terminal 11 and terminal 12 terminal are short-circuited

4-6. Terminal arrangement table

No.	Symbol	Function	No.	Symbol	Function
1	COM		20	CW	
2	DI1	1	21	COM	Control motor drive output
3	DI2	1	22	CCW	
4	DI3	DUinest	23	+	
5	DI4	DI input	24	_	AO Output
6	DI5] [25	COM	
7	DI6] [26 DO1	DO1	
8	DI7]	27	DO2	
9	+	Voltage(V) or Current	28	DO3	DO Output (DO1-3, DO4-6)
11	T –	(mA) Input	29	DO4	
10	+	Thermo couple or Voltage(mV)	30	DO5	
11	-	Input	31	DO6	
10	A		29	CW	
11	В	Resistance bulb input	30	СОМ	Feedback potentiometer input
12	b	1	31	CCW	
13	L		29	COM	
14	N	Power supply 90~204V AC	30	CT1	CT Input
15	СОМ		31	CT2	
16	EV1		32	+	AT : ±
17	EV2	EV output	33	_	AI Input
18	EV3]	34	SG	
19	+	0. + + 1	35	+	Communication RS 485
20		Output	36	_	
21	+	$O: \pm r: \pm 2/EV$ or $\pm r: \pm (EV/4)$	34	SG	
22		Output 2/Ev output(Ev4)	35	TXD	Communication RS232C
		·	36	RXD	

4-7. Rear terminal arrangement dagram

1	COM	25	COM				13	L		
2	DI1	26	DO1				14	Ν		
3	DI2	27	DO2				15	EV-COM		
4	DI3	28	DO3				16	EV1		
5	DI4	29	DO4	CC	M	CW	17	EV2		
6	DI5	30	DO5	СТ	1		18	EV3		
7	DI6	31	DO6	СТ	2	CCW	19	Out1 +		
8	DI7	32	AI+				20	Out1 -	CW	
9	+	33	AI –				21	Out2 EV4+	COM	
10	-	34	SG		SG		22	Out2 EV4 -	CCW	
11	+	35	+		Тхс	1	23	AO +		
12	-	36	-		Rxc	1	24	AO -		

5. Names and Functions of Parts on Front Panel



5-1. Explanation of each functions

(1)Display of measured value (PV) (red) Measured value (PV) and type of setting is displayed on each setting screen. ②Display of target value (SV) (green) Target value and set value are displayed on each setting screen. ③Pattern No, Display (Green) (PID No, on MAC6) Execution pattern No, (1-8) is displayed at program operation. Execution SV No, is displayed at FIX operation. (4) Step No, display (Yellow) (SV No, on MAC6) Execution step No, is displayed (1-96) at program operation. Execution PID No, is displayed at FIX operation. 5 Status LED Display RUN : Light on at RUN Operation, Blinking at Manual operation. AT : If AT is chosen in ON or external control input (DI), blinks during AT execution. Lights up when AT is on standby, and Off with AT automatic termination or release. PRG : On at the time of program control's standby or flat part control. Off at the time of FIX control selection. OUT1 : At the time of a contact or a voltage pulse output, On with ON and Off with OFF. At the time Current Output or a Voltage Output, OFF with 0% power output, and ON with 100% power. And blinks at intermediate ratio. OUT2 : Same as Output1 EV1: ON at the allotted event output turns to ON EV2~EV4: Same as EV 1 DO1: ON at the allotted event (DO) output turns to ON DO2~DO6: Same as DO1

GUA(Guarantee soak): ON at GUA function execution.

During program operation, the SV value on program step proceed to flat step from ramp step, the PV value some time delay from the SV value and the flat step become shorter than the step. This function avoid and assuring the time of flat step.

HLD: ON at Hold function execution

✓ (UP step) : ON at UP step execution

► (FLAT step) : ON at FLAT step execution

(DOWN step) :ON at DOWN step execution

6 Bar graph display (20 Dot LED)

Bar graph displayed Output value, Valve position, progress of the program operation by 0% to 100%. (5% per dot)

7Key-switch section

RUN (RUN) KEY:

Press for 3 seconds at STBY (control stop), then FIX or PROG control starts. Press for 3 seconds while FIX or PROG is in operation, then control is stopped.

MENU)KEY:

Press this key to move onto the next screen among the screens.

Press I (MENU) key for three seconds on the basic screen, then it jumps to the lead screen of Mode 1. Press I key for three seconds on the lead screen of each Mode screens, then it jumps to the basic screen. Press I key for three seconds on the lead screen of FIX or PROG, then it jumps to the basic screen. When a program control option is added, press I (MENU) key for three seconds on the screen of operation mode 2, then it jumps to the screen of operation Mode 1.

(Shift) key: Move the digit which set the value

The digit can be changed are blinked.

 $\mathbf{\nabla}$ (Down) key: One time press of $\mathbf{\nabla}$ key decreases by one numerical value. By pressing the key continuously, the value as well consecutively decreases.

A decimal point of the smallest digit blinks at this time.

▲ (Up) key : Press ▲(UP) key one time, and the shown value increases by one numerical value. By pressing continuously, the value consecutively increases. A decimal point of the smallest digit blinks at this time.

▲ and ▼ Key can be shifted to each lead screen from each mode screen.



▲ and ▼ Key can be shifted to SV No, 1-8 from FIX mode lead screen



▲ and ▼ Key can be shifted to Pattern No, 1-8 from Program mode lead screen.



Pattern

1

Pattern 2

Pattern 8

Pattern common setting

▲ and ▼ Key can be shifted to Step No.1-96 from Program step lead screen.



Image: Image

The setting data changed on each screen is determined. (The decimal point of the minimum digit is also lighted off).

Press the key for 3 seconds on the Mode 1 screen, then it shifts to Mode 2 screen.

Press three seconds on the monitor screen during RUN operation it shifts between Manual output and automatic output.

Push at FIX-PROG and each mode screens' lead screen, then shifts to setting screen.

PTN (Pattern) key (MAP6 only)

At a reset (RST) increment pattern No, on the basic screen

Press at the lead screen on the step setting screen, it sift to lead screen on the Program pattern setting screen.

STEP (Step) Key (MAP6 only)

Shift to Step1 lead screen of Pattern setting screen by pressing at PROG pattern setting lead screen. Press one second on the step setting screen, it shift to next step.



Pattern 1 Step 1

Pattern 1 Step 2



Step 96 Return to Step1

8 Infrared-ray communication port.

It can be communicated with MAP6 by USB adaptor and infrared-ray communication port. USB Adaptor available on Optional parts.

Details refer to communication instruction Manual.

6. Description of screens

6-1. How to move to another screen



Press the Ent key for three seconds on a basic screen, then it shifts to the lead screen of Prof. (program control) setting screens. F, C, G, (constant value control) setting screens, or to the lead screen of F, C, G, (constant value control) setting screens.

Press the mukey for 3 seconds on Financial or Prof. the lead screen of setting screens, then it shifts to the basic screen. The shift to $P - \sigma G$ is possible when the program option is selected at Mode2. The shift to $F \subseteq G$ is possible when the $F \subseteq G$ is selected at mode 2.

Basic screen



Every time you press the 📖 key on a basic screen, it shifts to each screen of the basic screens.

Press the 🕅 key for 3 seconds on a basic screen, then it shifts to the lead screen of mode 1 screens. Press the 🔺 key on the lead screen of mode 1 screens , then it further advances to mode 2, and mode 3.

(Notes: No corresponding if option is not found)

Press the 💌 key on the lead screen of mode 1 screens , then it further advances to mode 14, and mode13. (Notes: No corresponding if option is not found)

Press the 🕅 key for 3 seconds on the lead screen of mode 1~ 14 screens, then it shifts to the basic screen. Press the EMI key on the lead screen of mode 1~14 screens, then it shifts to the first setting screen of each screens.

Press the 📾 key on the first setting screen of each screens, then it shifts to the next screen. Every time you press the 📾 key, it shifts to the next setting screen.

6-2. Setting method

To change settings, display an appropriate screen and change the setting (value or function) by pressing \blacktriangle or $\mathbf{\nabla}$ key. and determine buy pressing \mathbf{w} key.

On the output monitor screen of basic screens, you can change the control output from "Automatic" to "manual", and save its change of setting. Display the output monitor screen, and then press is key for three seconds to shift from Automatic to Manual.

Then by pressing \blacktriangle or \bigtriangledown key, you can adjust to the desirable output value. In this case, no need to press \bowtie key in order to determine the change of setting.

Press \mathbb{M} key for three seconds as well to shift back to Automatic. Excluding when a keylock is OFF, Automatic \Leftrightarrow Manual switchover does not work while STBY<RST> and AT are in operation.

In the case of two-output type, the switchover between automatic and manual is operatable through output 1 and output 2. The setting is altered simultaneously.



6-3. Power ON sequence

At power-on, the display section shows each screen of initial screens for one second , then moves on to the basic screen.



6-4 Explanation of each basicscreen

Basic screen



MENU

	Executed SV							
	Initial value	Sensor input : 0						
		Linear input : Lower limit of scaring						
	Setting range	Sensor input : Within measuring range						
		Linear input With in scaring range						
		Within SV limiter besides						
	Targeted value (PV) is d	isplayed on the upper row as 5–digit, and target value (SV) is						
	displayed on the lower re	ow also as 5-digit.						
(Notes: hereinafter, measured value and targeted value are referred to as ${ m `PV''}$ and ${ m `'}$								
At the time of FIX, execution SV is displayed and change of setting is possible.								
	PROG's SV is just displa	yed, and change of setting is impossible.						
	During AT execuiting an	d Key lock level 2–4 are set, setting is impossible						
At the time during AT and key lock level 2–4 is set, change of setting impossible.								
	Execution Program No.	can be changed by pressing 🎮 at the RST in Program.						
	When no key operation 3 minutes or more, screen will be shifted to basic screen or the							

When measuring range, unit and scaling value changed, parameter will be initialized.

Action Mode 1





screen of DI super keylock.

Action Mode 2



 Initial value : Pro5 Setting range : Pro5, F55

During no operation the display will be - 5 ← (Program) or 5 ← 5 ⊕ (FIX).
Choose R key and decided by R key then Monitor LED's RUN lights up to start control operation.
Choose 5 ← 5 ⊕ (- 5 ←)by ▲ key, Decide by R key, Then Monitor LED's RUN lights off and becomes control stop [Output OFF (0%)] conducting.
Priority is given to DI function, when RUN is allotted to external control input. DI. Key operation cannot be performed unless allotment is canceled.

Press Evil key for 3 seconds, then it shifts to Action mode2 screen, when the program control option is added on this screen, FIX (constant value control) $\leftarrow \rightarrow$ PROG (program control) switchover is possible choose(Choose a program, then Monitor LED's PRG lights up.

Press Mewkey for 3seconds then it shift to Action mode 1.

Priority is given to DI function ,when PROG is allotted to external control input. DI. Key operation cannot be performed unless allotment is canceled.

Press Mey then it shift to Output 1 monitor screen.

When measuring range, a unit, scaling, and output characteristics are changed, parameter will be initialized and $5 \succeq b \exists (r = 5 \succeq)$ is display.

Output 1 monitorscreen



Manual output setting range : 0.0-100.0% (within output limiter)

At the time of automatic output, monitor display only.

Refer to automatic ⇔ manual switch over, and setting method at the time of manual operation.

A manual output is canceled when an operation mode is made into 5253 (-52).

When a power source is intercepted and re-switched on, it returns to the condition just before intercepting.

When \overrightarrow{R} \overrightarrow{R} \overrightarrow{n} is allotted to DI, DI is given priority. Automatic \Leftrightarrow manual switchover is not performed with key operation, and only the output value at the time of manual operation can be changed.

During AT executing or Key lock level 3-4 are set, setting is impossible

Output2 monitoring screen



Contents are the same with that of an output 1

Output 2 monitoring screen displays only when output 2 option is added.

CT1 monitor



menu

MENU

Display range: 0.0~55.0A

Displays at the time of CT input option addition, and the current value detected by CT Sensor is displayed.

Upper Display: PV value Middle Display: Current value Lower Display: Detected CT sensor (CT1) Program step time period Display screen



Display Range : 000:00 - 3000:00 or ∞ (infinity) Upper Display: PV value Middle Display: Time remain Lower Display: Pattern No, & Step No, Displays while program is in operation. On-going step No. and the remaining repeating time of pattern are displayed A remaining time and an elapsed time is switchable by pressing the EM key for 3 seconds. (Switchover is interlocked with the number of times of next screen we pattern.) In ∞ setting, remain time σ^{Φ} are displayed. This screen is not displayed Program RST and FIX neither.

Program repeating time of pattern





PID monitor screen



Display range : PID1 - PID8 PID No. is displayed when FIX is in operation. PID No. chosen at each step and on-going step No. are displayed by turns when PROG.

External analogue input (AI)monitor screen.



External Analogue input Value which selected at Mode10 is displayed. This screen is not displayed without an AI option and status Non at Mode 10.

Middle Display: Number of reputationtime Lower Display: Pattern No, & Step No,

Upper Display: PV value

Display range : 0 −30000 or ∞

On-going step No. and the remaining repeating time of pattern are displayed. A remaining time and actually performed times are switchable by pressing the **ENT** key for 3 seconds. (Switchover is interlocked with front screen step time.) The decimal point of the minimum digit lights up when actually performed times being displayed.

In ∞ setting, step No. and $\Box \Box$ are displayed This screen is not displayed Program RST and FIX neither.

No displayed in the state of STBY (RST). No display at FIX mode.

Servo output position monitor screen



Display range 0.0 – 100.0 % Servo output position is displayed. This screen is not displayed without Servo output option and feedback input.

Hold execution screen

ЙаЫ	88
NATE 1995 RUN 0171 0072 201 0072 101 007 101 0	866 8.88
PTN STEP	00
MENU < 🖂	ENT
MAPGA	SHIMA



While HOLD is executed, on the basic screen, SV value and H_{OL} is displayed by turns. If switched $\Box \cap$ while PROG is in operation, the operation temporary stops with as of then step time and SV value. While HOLD is in execution, SV value and H_{OL} is displayed by turns in basic screen. HOLD is used in order to perform AT in the middle of an inclination step or to compensate the insufficient time of flat step. Controls is performed with SV value at the time of stopping, while HOLD is in supervision HOLD is in

execution HOLD is canceled if $\sigma F F$ is chosen while HOLD is in execution. The remaining time of the step is performed based on a program.

5 $H_{-}P$ (skip) is unable to perform while HOLD is in execution When $H_{-}L_{-}d$ is allotted to DI, DI is given priority. Execution and release of HOLD with key operation is unable to perform. This screen is not displayed the state of program $-5L_{-}$ and FIX neither.

Skip execution screen



MENU

Initial value: oFF Setting range: oFF. on

SKIP (skip) is the function that makes to end the on-going step compulsorily, and is to shift to the following step. The next step starts instantly, if performed. When SKIP is continuously performed, about 1 second interval is required from execution to the next one.

Even if SKIP is allotted to DI, execution is able to perform with DI and key operation. Not displayed in the state of program -52 and FIX neither.

Program pattern No, selectionscreen



Initial value:1 Setting range:1-8

The number of setting in the program pattern screen can be changed 1–8 to the number of program pattern. Only the pattern you did program pattern setting screen will be indicated.

Not displayed in the state of FIX operation



FIX execution SV settingscreen Initial Value: 1



Setting range: $1 \sim 8$ SV setting screen. Not display in the state of Program operation.

AT (Auto Tuning) execution screen



MENU

Initial Value: **____FF** Setting Range: **____FF**, **____n** AT is performed by ON selection, and canceled by OFF selection. Not displayed at the time of STBY(RST), a manual output, and P(proportional band) =OFF. Except in the setting of keylock OFF, AT is unable to perform in scale over, and even in such a case, halfway release is performed on this screen. (At the time of DI allotment, execution of AT by DI can be performed.) Release of AT, STBY(RST), EV operating point, setting of keylock, and mode 6,7,9,11,12 and 14 are operatable with key. Except in the setting of AT normal end, execution of AT is canceled compulsorily at the time of time over (200min) scale over STBY(RST) selection and AT release setup.

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EV 1 lower operating point setting screen



The operating point of the alarm type allotted to EV1 is set up. No display when no EV option installed or $\neg \circ \neg$, $5 \circ$, $\neg \circ \neg$, $H \circ L \circ$, $P - \circ L$, d - SL, u - SL, $G \circ R$, and $E S : ~ E S \circ H$ are allotted to EV1. The operation mode of each deviation alarmis $\neg \circ \neg$ Effective at the time of automatic output. Each deviation alarm serves as PV's deviation to Execution SV. Event operation other than each deviation alarm is always effective. In case of -100.0 to -0.1 set at SEP PE, and $E \cap \sigma O$ EV will be activated before the time set to the End.

(When -10.0 sec set, EV will be activated 10.0 sec before 10.0 sec to the End, when 10.0 sec set EV will be activated 10.0 sec from the End, In case of 0 sec set no signal will be activated even if allotted)

Function		
Upper limit absolute value alarm	HR	Belong to Range settingand scaling
Lower limit absolute value alarm	18	Belong to Range settingand scaling
Upper limit deviation value alarm	На	-20000~30000 unit
Lower limit deviation value alarm	Lð	-20000~30000 unit
Within deviation alarm	Ēð	<i>0~30000</i> unit
Without deviation alarm	od	0~30000unit
CT1 Control loop alarm (heater braking)	ct :_b	0.0 ~ 50.0A
CT1 Control loop alarm(loop)	ct /_L	0.0 ~ 50.0A
CT2 Control loop alarm (Heater braking)	ct2_b	0.0 ~ 50.0A
CT2 Control loop alarm (loop)	c22_L	0.0 ~ 50.0A
3 phases control loop alarm (Heater braking)	ct3_b	0.0 ~ 50.0A
3 phases control loop alarm (loop)	ct3_L	0.0~ 50.0A
Step signal	SEP	100000 ~ 100000 sec
Pattern end signal	P_E	- 10000 ~ 10000 sec
Program end signal	End	- 10000 ~ 10000 sec

There are 4 kinds of setting in Event setting.

The 1st Event setting is the setting method explained by the above.

Additionally according to the SV number (FIX operation),to the each Step setting, and to the each program pattern setting.

Character of these Event setting are

SV Number 58_ ~

Pattern PL- (MAP6)

Step 566 (MAP6)

Setting method of each Event setting is included in each setting screen.

EV1 Lower operating point setting screen



Initial value: Minimum value of setting range. Display when EV1 allotted to $\overline{}$ or $\overline{}$ R

EV1 Upper operating point setting screen



Initial value : Maximum value of setting range Setting range : within measuring range Display when EV1 allotted to **7** or **7** or **7**

EV2-EV4 operating point setting screen



The operating point of the alarm type allotted to EV2 - EV4 is set up. Details are same as EV1.



No display when no EV4 installed. Details are same as EV1.

External operation output (DO)Setting screen



The operating point of the alarm allotted to DO1 is set up.

are allotted to DO1.

The operation mode of each deviation alarm is **run** effective at the time of automatic output.

Each deviation alarm serves as PV's deviation to Execution SV. Event operation other than each deviation alarm is always effective.

In case of -100.0 to -0.1 set at $5 \succeq P$ PE, and $E \neg d$, EV will be activated before the time set to the End.

(When -10.0 sec set, EV will be activated 10.0 sec before 10.0sec to the End, when 10.0 sec set EV will be activated 10.0 sec from the End, In case of 0 sec set no signal will be activated even if allotted)

DO1 lower operating point setting screen



Initial value : minimum value of settingrange Setting range : within measuring range Display when DO1 allotted to $\overline{}$ or $\overline{}$ R

DO1 upper operating point settingscreen



Initial value : Maximum value of settingrange Setting range : within measuring range Display when DO1 allotted to **_ ?** or **_ ?**



MENU

DO2 - DO 6 details are same as DO1 No display when no DO option installed.

Latching release screen



Initial value: EB / Setting range: EB / EB2 EB3 EB4 do / do2 do3 do4 do5 do ALL.

On the latching setting screen of each EV and DO mode, $\Box \neg$ and $\Box \downarrow$ which chose $\Box \neg$ are displayed.

If latching is $\Box \neg$ once EV and DO are outputted, output state are maintained even if the state of OFF. When EV and DO are in a latching state, decimal point of the minimum digit blinks, and it shows that release are possible. If \mathbb{N} key is pressed, EV and DO released and a decimal point lights off. However, release is impossible when a state is in EV or DO power range.

MENU

No display when no EV and DO option are installed or all setting of Latching OFF.

Return to Basic screen



6-4. PROG (program control) setting screens

Press Ent key for 3 seconds, lead screen of the PROG setting screens is displayed, When program option is added and **Pro 5** is chosen on Action mode2 screen of basic screens.

If me key is pressed for 3 seconds on lead screen (1to 8 or ALL), it returns to basic screen



Program pattern 1 leadscreen



Press ▲ or ▼ at Program pattern 1 lead screen it shift to pattern 2·3·4·5·5·7·8·8:2: · · · screen.



Press ^{STEP} each lead screen of program pattern it shift to Step setting screen. Press ^{PTN} each step screen it shift to lead screen of program pattern setting screen.



6-4-1. Program pattern common setting screen

00

SHIMA

PTN STEP

MENU



Press ENT Key, it move to time unit setting screen

Time unit setting screen





Number of pattern settingscreen





Initial Value : / Setting range : / MAX 96steps

 \mathbf{Z} MAX 48steps each pattern

∃MAX 32steps each pattern

HMAX 24steps each pattern

5 MAX 16steps each pattern

BMAX 12steps each pattern

6-4-2. Each program pattern setting screen





Start mode setting screen



Setting range : 5B(SV), PB(PV)

Initial value : 58

This setting screen can decide if the start set point of program control should be PV, or should be the start SV which is set on the next screen.

When PV is chosen, and when PV is closer to the set point of Step1 than start wasting SV, time is omissible.

Start SV setting screen

MENU





End step setting screen



Initial value : At the type of sensor input linear input type scaling lowerlimit Setting range: sensor input type within measuring range linear input type within scaling range Moreover, within limit of SV limiter. When SV is chosen on start mode setting screen, this screen's set value becomes

start set point. The basic screen SV display at the time of Program RST is the value set on this screen.

Initial value: 96 Setting range: 1-96 steps Pattern termination step No, of program control is set. Number of Pattern 1: Max 96steps Number of Pattern 2: Max 48steps each step Number of Pattern 3: Max 32 steps each step Number of Pattern 4: Max 24 steps each step Number of Pattern 6: Max 16steps each step Number of Pattern 8: Max 12steps each step

Number of execution setting screen for repeating of program pattern



Initial value:1 Setting range:1 \sim 30000 or ∞ The number of execution of a program pattern is set.

Guarantee soak zone settingscreen



Initial value: OFF

Setting range:OFF,1 \sim 10000 Digits(Time unit belong to the Time unit setting screen) During program operation, the SV value on program step proceed to flat step from ramp step, the PV value some time delay from the SV value and the flat step become shorter than the step. This function avoid and assuring the time of flat step.

Pattern EV1-4 setting screen



Each pattern EV setting screen is displayed at EV1 \sim EV4 is allotted to P_{E} \rightarrow at EV setting screen in Basic screen.



Pattern setting lead screen



About PV start

In start mode, when PV is chosen, and when PV is closer to the set point of Step1 than start SV, wasting time is omissible.

[example]:PV at the time of "RST is 30°C, Start SV is 0 °C, Step 1's attainment SV 100 °C, Execution time of Step1 is 60 minutes

Start at start SV, attainment time is 60 minutes.

When starts at PV, $100-30=70^{\circ}$ C, therefore 60 minutes $\times 70\% = 42$ minutes = 18 minutes' shortening

However, depending on the spatial relationship between PV, Start SV, and attainment SV, it may become SV start or Step1 may be skipped.



6-4-3. Each program step setting

Program step setting leadscreen







Initial Value : 1 Setting range :1 \sim 8 Step1 output1 PIDNo. setting screen It have to be used both Out 1 and Out2.

Time signal 1 ON time setting screen



Initial value: **_F** Setting range :00:00 ~300:00 (min:sec Hour:min) 0.0 ~3000.0(hour)

About time signal

ON time is the time that will be ON after step bigan.

Time signal setting screen is displayed at EV or DO I is allotted to time signal. Time signal setting has to be OFF when time setting is longer than step time. When only ON time setting is set, it keep status ON until other step will be OFF. When hold function is activated at program function, time signal Time also stops temporarily.

Time signal ON statue have to be finish compulsorily in pattern end.



MENU

Time signal 1 off time setting screen



Initial value: $\Box FF$ Setting range : 00:00 ~ 300:00 (min : sec, hour : min) 0.0 ~ 3000.0 (hour) OFF time is the time that will be off after step bigan.

Time signal 2 ON time setting screen



Same as Time signal1

Time signal 2 off time setting screen



Same as Time signal 1
Time signal 3 ON time setting screen



Same as Time signal1

Time signal 3 off time setting screen



Same as Time signal1

Time signal 4 ON time setting screen



Time signal 4 OFF time setting screen



MENU

Same as Time signal1

Independent EV setting screen



Setting range : Chosen from event type character Each Event output from table below at Mode6

Event mode	
Upper limit absolute value alarm	HR
Lower limit absolute value alarm	12
Upper limit deviation value alarm	Нd
Lower limit deviation value alarm	Ld
Within deviation alarm	īd
Without deviation alarm	0d

Independent EV setting screen in the numerical value territory area of the Event operating setting screen in the Basic screen.

Independently setting can be enable at the setting of $\mathbf{5}\mathbf{E}\mathbf{E}\mathbf{P}$.



Step1 setting lead screen

6-5. FIX (constant value control) setting screens

 $\leq \nabla \land$

MENU

MENU

ENT

When $F_{\overline{}}$ is chosen on Action mode2 screen of basic screens, lead screen of FIX setting screens is displayed when $\overline{\mathbb{E}}$ key is pressed for 3 seconds at the basic screen.

If 🞟 key is pressed for 3 seconds on lead screen of SV1 – SV8, it returns to basic screen.



Press ▲ and ▼ at SV 1 lead screen it move to SV2 SV3 SV4……





STEP

MENU < V

Ramp time unit settingscreen Initial Value : mm : ss Setting range : h.hhh , hh : mm,mm : ss

Ramp time setting screen

Initial value : 0 Setting range : 0.001~30.000 or 000,01~300,00

6-5-1. Explanation of Ramp & Soak function

00

A ENT

SHIMAX Ramp & Soak function is the function can be

- 1) SV change (key and DI) and the Rump start Trigger condition for STBY RUN can be chosen.
- 2) PV start Mode can be chosen.
- 3) It's possible to set Rump time and Soak time separately.
- 4) Automatic distinction in the slope direction (Up/Down)
- 5) It's possible to allot Ramp Status (Ramp ON/OFF_Delay signal) to Event/DO.
- 6) It's possible to allot Soak Status (Ramp ON/OFF_Delay signal) to Event/DO.

1. Ramp start trigger

Ramp mode setting can choose effectively/invalidly from below:

Trigger A Status will be changed by Power supply ON, or from DI signal during RUN status.



🖸 : Invalid

- : It will calculate Start SV Value will be Start SV, Setting SV will end SV value.
- 2 : It will calculate PV will be Start SV value, Setting SV will be end SV value

Triger A Example of Trigger A



Trigger B SV No, changed from Key or DI signal



Invalid
 It will calculate SV value just before status changed will be start SV, SV value after status changed will be end SV value



Trigger C SV value changed for manual key operation



- 🖸 : Invalid
 - I : It will calculate SV value just before status changed will be start SV, SV value after status changed will be end SV value

Example of Trigger C



PV start operating example

Status will be changed by Power supply ON, or from DI signal during RUN status.





①AT will be waiting when AT starting during Ramp is execute, and AT will be start after Ramp will be finish.



②It cannot be accepted DI signal and SV value changing during AT is executing, therefore Ramp function cannot be operated Ramp function can be repeated

(When the temperature difference is different, the slope is also different inevitably.)



③When SV Value or SV No, changed During Ramp function is proceeding, Once time have to be initialized and calculate Ramp rate again using changed SV value to Start SV.

(Ramp Rate and Ramp time will be changed)



(4) When Ramp time will be changed during Ramp function is proceeding, time have not to be initialized. It will be calculated by using remain Ramp time.



(5)When SV No will be changed during Ramp function is proceeding, time have not to be initialized. It will be calculated by using remain Ramptime.



Explanation of Ramp status and Soak status

1:In case of Ramp Status ,timer starting at Ramp start

2:In case of Soak Status timer starting at Ramp finish

3:No Event activating at Status time >Ramp time at Ramp status mode 1

4:Even will be on at the status time > Ramp time at the Ramp mode2

Status operation example



Power failure compensation

When set the Power failure compensation is activate , Ramp function have to be start at the first value. But in case of PV start has set , Ramp function have to be started like below:



Power failure compensation ON (SV Start)

Ramp status, Soak Status Special case matter

Soak status can be released by , power off ,next Ramp start and Event mode change at Event Latching OFF.



At the status of EV Latching ON, Soak signal can be released by power off or EV latching off. Soak signal will be turned off when timer cleared. (Latching off status)

 $\mbox{Event/DO}$ cannot be activate when SV No, changed before Status time is not up. Operation example of repeat Ramp operation



Soak signal can be allotted without Ramp function. But this is only like time signal.



SV 1 settingscreen



SV1 PID No, setting screen



Initial Value :	At the time	At the time of sensor input 0		
	linear input	time scaling lower lin	nit	
Setting range : sensor input time within measuringrange				
		linear input time v	vithin scaling range	
		Moreover, within lir	nit of SV limiter.	
When SV1 is Exec	ution SV, being r	eflected in basic scre	een.	
Being initialized wh	nen measuring ra	nge, unit, and scaling	are changed.	

Initial Value : 1 Setting range : 1, 2, 3, 4, 5, 6, 7 and 8. When SV1 is Execution SV, PID No. that will be used is chosen from $1\sim 8$.

EV operation points of each SV1 \sim 8 setting screen is displayed at EV1 \sim 4 operating point is set $5H_{-}$ at basic screen on FIX operation. Being initialized when Event mode are changed.



6-6. Mode setting

Press the \mathbb{H} key for 3 seconds on a basic screen, then it shifts to the lead screen of mode 1 screens. It can be shift from Mode1 to mode14 by pressing \blacktriangle and \mathbb{V} key.



6-6-1. Mode1 System setting

Mode 1 setting lead screen



Press 📾 key for 3 seconds on basic screen, then displayed

Press the x key, then it shifts to the first setting screen, keylock setting screen. Press x key to each mode setting screen. Press x key to advance each setting.

Key lock setting



- Initial value : OFF Setting range: OFF 123458
- ? Possible to operate except for RUN key ,key lock level, Mode $1 \sim 14$.
- Possible to operate execution SV value , Manual value , We key key lock level, Functions in Basic screen and functions in Step setting.
- 3 Possible to operate Execution SV value ,Manual value 🕅 key and key lock level,
- └ Possible to operate Manual value and [™]key and key lock level.
- **5** Possible to operate of keylock level and **Run** key.
- **5** Possible to operate of keylock level.

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SV limiter lower limit settingscreen



Initial value: measuring range lowerlimit

Setting range: measuring range lower limit value to measuring range upper limit value -1.

When upper limit value is smaller than lower limit value, the value compulsorily becomes lower limit value+1.

SV limiter upper limit value setting screen



Initial value : measuring range upper limit Setting range : SV limiter lower limit value +1 \sim measuring range upper limit value

Bar graph setting screen



Initial value: non Setting range: PH-5H(PV-SV deviation value) out: (OUT1 output rate), out 2 (OUT2 output rate) 5_t: (Step time rate)

P___(program pattern execution number)

580Fb (Servo out position)

Bar graph displayed Output value, Valve position, progress of the program operation by 0 to 100%. (5% / dot)

MENU

When bar graph is allotted to program functions, Execution finish will be "ON" and will be "blinking" during execution.

When it set ∞ at Step time rate, bar graph lighting up repeated in left and right.

LED brightness setting screen



Status LED Mode setting

PV		
	HH	HH
L.		
SIN AT P	svee	A'A A
0JT1 0JT2		
EV1 EV2 201 202 20	EUA 13 204 205 204	H HH
PTN	STEP	00
MENU	$<$ \vee	ENT
MAP6A		SHIMAX

Initial Value: 3

Setting range: 1, 2, 3 & 4 LED brightness can be changed by 4 levels, Please adjust it according to the environment.

Initial value : 1

Setting range : 1, 2 & 3

- 1: Lighting during the functions are executing
- 2: Dimness lighting at option function are installed and lighting during the function is executing.
- 3: Dimness lighting at option function are installed and allotted. Lighting during the functions are executing.

Power failure compensation setting screen

ŠAU	E .8.
RUN RUN 0171 0172 201 017 201 017 201 017 201 007 201 007 201000000000000000000000000000000000	388 8.88
PTN STEP	00
MENU < 💟	ENT Shimax





MENU

Initial value: **_F** Setting range: **_F**, **__**, **__**, Power failure compensation is the function that can be remained the status of operation before power failed. It can be started up same status of operation again. Step time of program function at power failure is not compensated.

Initial value: 1

Setting range: 1,2

(1: given to the priority to stability.,2:given to the priority to followingness)

When PID 2 is chosen, ABC parameter will be appeared at Mode3. When PID method is changed during RUN status, status move to STBY. Please refer to the explanation of PID method page 61. Sampling period time settingscreen



Initial Value : 167 Setting range : 50, 167, 250, 500ms

Sampling period time can be set according to each application. Being initialized when sampling period is changed.

Mode1 lead screen

6-6-2. Mode2 PV setting screen

Mode 2 setting screen lead screen.



PV offset correction (PV bias) setting screen



MENU

Initial Value : 0.0 Setting range : -5000~5000digit Used for correction of input errors such as sensor. If offset correction is performed, control is also performed with the corrected value

PV gain correction setting screen



Initial value : 0.000

Setting range: $\pm 5.000\%$

Maximum input value is corrected within limit of ± 5.00 % of measuring range. If corrected, inclination of span changes in straight line which connects zero point and correction maximum value.





MENU

Initial value: 0 Setting range: 0~10000sec When input change is violent or noise is overlapped, used in order to ease the influences. In 0 second setting, filter does not function.

Measuring range setting screen





Initial value: H : Setting range: Chosen from 5–5.measuring range code table. Combination of input type and measuring range is set by code. Being initialized when measuring range is changed.

Temperature unit setting screen



Initial value : Setting range : The temperature unit at the time of a sensor input is set up from (°C) (°C) (°C) Not displayed when linear input is chosen. Being initialized when temperature unit is changed.

Cold junction compensation setting screen

HHH	HH.
SV	FAR
	0 00
001 002 003 004 005 008	
PTN STEP	00
MENU < 🗸	I ENT
MAP6A	SHIMA

Initial value : Internal

Setting range : External

It can be choose cold junction compensation functioned from internal circuit or from external equipment at thermo couple input.

No display when linear input or resistance bulb input is chosen.

Input scaling lower limit value setting screen



Initial value : 0.00 Setting range : $-20000 \sim 31990$ Scaling lower limit value at the time of linear input is set up

Input scaling upper limit setting screen



MENU

Initial value : 100.00 Setting range : -19990 ~ 32000 Scaling upper limit value at the time of linear input is set up Suppose that the difference between a lower limit value and upper limit value is 10 or less, or over 50,000. In this setting, upper limit value is compulsorily changed into that of +10 or \pm 50,000 count. Upper limit value cannot be set as lower limit value of +10 count or less, or that of over 50,000 count.

▼ Input scaling Decimal point position setting screen



MENU

Initial value : 0.00

Setting range: no decimal point 0~the 4th place after decimal point (0.0000) Decimal point position of input scaling is set The screen of input scaling serves as a monitor at the time of a sensor input. Setting change cannot be performed. Being initialized when decimal point is changed.

PV limiter lower limit settingscreen



Initial value : -10% of measuring range Setting range : $-10\% \sim 110\%$ of measuring range (within $-19999 \sim 32000$) Under scale point (\underline{L} \underline{L} \underline{L} \underline{L}) is set. PV limiter upper limit setting screen



Initial value : 110% of measuring range. Setting range : -10% ~110% of measuring range (within -19999~32000) Upper scale point (HHHHH) is set.

Mode 2 lead screen.

6-6-3. Mode3 Out1 setting



MAP6 has 8kinds of PID setting (PID1~PID8) both Out1 and Out2. It can be moved PID1 to PID 8 by pressing shift key.



Mode3 PID1 lead screen



Output 1 PID1 proportional-band (P) setting screen



Initial value : 3.0% Setting range : OFF, 0.1 \sim 999.9% When performing auto tuning, no necessity for a setting basically. If OFF is chosen, it becomes ON-OFF (two positions) operation.

Output 1 PID1 Integral time (I) setting screen



Initial value : 120 seconds Setting range : 0FF, 1~6000 seconds When performing auto tuning, no necessity for a setting basically. This screen is not displayed at the time of ON-OFF operation. Becomes P operation or PD operation in I=OFF setting.

Output 1 PID1 Derivative time (D) setting screen



MENU

Initial value : 30 second Setting range : 0FF, 1 \sim 3600 seconds When performing auto tuning, no necessity for a setting basically. This screen is not displayed at the time of ON–OFF operation. Becomes P operation or PI operation in D=OFF setting.

Output1 PID1 manual reset setting screen



Initial value : 0.0(Output 1) -50(Output1 & 2) Setting range : -50.0~50.0% The offset correction at the time of I=OFF (P operation, PD operation]) is performed. This screen is not displayed at the time of ON-OFF operation.

Out1 PID1 Lower differential-gap setting screen



Initial value : 5 digit Setting range : $1 \sim 9999$ digit The differential gap at the time of ON–OFF operation lower point is set. Displayed at the time of P=OFF (ON–OFF operation) setup.

Out1 PID1 Upper differential-gap setting screen



Initial value : 5 digit Setting range:1 \sim 99999digit The differential gap at the time of ON-OFF operation Upper point is set. Displayed at the time of P=OFF (ON-OFF operation) setup.



Out1 Flex PID factor A setting screen.



Initial Value : 0.20 (program operation) 0.40 (Fix operation) Setting range : 0.00 ~1.00 Display at the time of PID methiod is set 2. Initialaized at Program and Fix has changed. Refer to Explanation of Flex PID method Display at the time of PID method 2

Out1 Flex PID factor B setting screen.

PV	
HHH	HH
	U.C.U
0011 0012 / → EVT EVZ GEA 001 002 903 004 005 004	B. B.B
PTN STEP	00
MENU < 🗸	▲ ENT
MADGA	SHIMAX

Initial Value:0.20 (program operation) 1.00(Fix operation) Setting range:0.00 ~1.00 Display at the time of PID method is set 2. Initialized at Program and Fix has changed. Refer to Explanation of Flex PID method Display at the time of PID method 2

Out1 Flex PID factor C setting screen.



Initial Value : 0.40 (Output 1 character and Output2 character are same) 0.80 (Output 1 character and Output2 character are different) Setting range : 0.00 ~ 1.00 Display at the time of PID method is set 2. Initialized at Program and Fix has changed. Refer to Explanation of Flex PID method Display at the time of PID method 2

Output1 PID1 minimum limiter setting screen



Initial value : 0.0 Setting range : 0.0~99.9% Output lower limit value of output 1 PID1 is set.

Output1 PID1 maximum limiter setting screen



Initial value : 100.0 Setting range : 0.1~100.0% Setting range: output limiter lower limiter values +0.1~100.0%

Mode3 PID1 lead screen

About Output limit function.

At the time of Reset (standby) and Over scale, Output have to be 0.0% compulsorily with. nothing relate output limit setting value.

During AT tuning function, output value will be 0% and 100% with nothing relate output limit setting value. At P=OFF operation Output type C and S will be 0% and 100% with nothing relate output limit setting value. Please refer the table below:

AT P = OFF S, C S, C I T 0.0 0.0 0.0 OL or or or or 100.0 100.0 100.0 OH

At the time of difference between Output maximum limit value and minimum limit value will be less than 0.1, it have to be set the maximum limit value, +0.1 to minimum limit value.

Out1 PID common setting Common setting of PID can be moved from PID8 screen.



√ Shift key

Out1 PID common settingscreen



Out1 Soft start settingscreen



Initial value : Off Setting range : Off, 0.1 ~ 300.0 sec This is the function that eases change of output at the time of a power-on and startup from 0% to 100%. Does not function at the time of OFF setup.

Output 1 proportional periodic time setting screen



Initial value : 30.0 (Contact) 3.0 (Voltage pulse) Setting range : 0.5 ~300.0seconds (setting resolution 0.5seconds) Proportional periodic time of output 1 is set. No display beside Contact and Voltage pulse

Output 1 characteristics settingscreen



Initial value : RA

Setting range : RA, DA

Characteristics of control output is chosen from RA (heating characteristics) and DA (cooling characteristics)



Out1 PID common settingscreen

6-6-4. Mode4 Out2 setting

Mode 4screens is the setup screens of output 2 option. Not displayed when option is not added. Mode 4 has PID dead band setting screen (

Out2 PID1 lead screen





Dead band setting screen



Initial value: **DD** Setting range: -20000~30000digit



Same as Out1

Out2 PID1 lead screen

Out2 PID common setting

Out2 PID common setting lead screen





Out2 PID common character setting screen



Initial value: **JR** Setting range: **-R**, **JR**

Explanation of 2 output-characteristics figure

Two output characteristics is shown in the following figure.

 \bigcirc Conditions: P operation, manual reset ($\overline{-}$) = -50.0%



control output 1 (RA characteristics) control output 2(DA characteristics)







Explanation of PID method.

MAC6 equipped with flex PID which can be suited SV (target value) change followingness as a disturbance in addition to the usual type SHIMAX PID which can be suited for a few target of a disturbance element (factory setting)

This is explainaton a modification method of two types PID method both SHIMAX PID methid and Flex PID method.

Adjustment of each Factor

Auto tuning function calculates standard PID for the turbulence response but best value is not necessarily obtained for all applications.

When the auto tuning function finished, it should be confirmed whether the auto tuning result is excellent by giving turbulence by intention while checking the control result.

The integration limitation coefficient is trimmed 🛴 as an adjustment of the overshoot and undershoots. When

🗧 is enlarged, it becomes easy for the overshoot and undershoot to go out though the restoration speed quickens.

∑ setting range=0.00~1.00 ∑ Default Value(Value of Output1 0.4 as same Output 1 &2)

(0.8 As Reverse-characteristic Output 1& 2)

Adjustment of follow for Start up and SV change

The turbulence response and the SV change follow can be individually set by Flexible PID method in MAC6. It already set up the turbulence response, and now set it according to the purpose based on the table below.

8	Ь	Control method	Features	Remarks
1	1	I-PD (Measurements proportion differentiation early type)	For fixation control	
1	0	ID-P (Measurements proportionally early type)	The kickback by the SV value change is inferior	1 Flexible PID
0	1	IP-D (Measurements differentiation early type)	follow are a little inferior. For ramp control	control
0	0	PID (Deflection PID)	For target value follow valuing and cascade regulation	
8	0	P-I-PD(P2 flexitype)	Turbulence response and target valuefollow	Like 2 flexible PID control
8	n se	tting range=0, $00 \sim 1, 00$	Default value (FIX: $B=0.40$ $h=1.00$)

(PRG: *R*=0. 20 *b*=0. 20)

 \boldsymbol{R} should be reduced when you want to improve the step response at the SV change and the startup, \boldsymbol{R} should be expanded when you wants to reduce the overshoot at the step responds and to reduce the output change.

b should be reduced when you want to improve the follow performance at the lamp control, b should be expanded When you wants to reduce the overshoot at the lamp ends and to reduce the output change

6-6-5. Mode5 Zone PID setting screen



This function can be set up to 4 differences PID Zone in measuring range. Most suitable PID value can be set in each measuring zone, and it have to be controlled suitable for the condition of each application.

Zone PID setting screen



MENU

Initial value : OFF Setting range : OFF, SV,PV Zone PID function can be set by PV Value or SV value.

Being initialized when measuring range and scaling changed

Zone 1 SP (set point) settingscreen



MENU



Initial value : 0.0 Setting range : within measuring range ,scaling range and limit setting. Change PID No, at set point. No display at Zone PID OFF. Being initialized when measuring range and scaling changed

Zone 2 SP (set point) settingscreen



Initial value : 0.0 Setting range : within measuring range ,scaling range and limit setting. Change PID No, at set point. No display at Zone PID OFF. Being initialized when measuring range and scaling changed

Zone 3 SP (set point) settingscreen



Initial value : 0.0 Setting range : within measuring range ,scaling range and limit setting. Change PID No, at set point. No display at Zone PID OFF. Being initialized when measuring range and scaling changed

Zone 4 SP (set point) settingscreen



Initial value : 0.0 Setting range : within measuring range ,scaling range and limit setting. Change PID No, at set point. No display at Zone PID OFF. Being initialized when measuring range and scaling changed

Zone hysteresis setting screen





Initial value : 2.0 Setting range : $0 \sim 9999$ digits



*Zone hysteresis is set as the lower side of the SP Value. *When same value is set in plural SP value, priority is given to younger SP Number.

6-6-6. Mode6 Event 1~4setting

Mode 6 screens is the setup screens of event $1 \sim 4$ option. Not displayed of Event 4 when option is not added. Press shift key to shift EV1 \sim 4.



Event 1 operation-mode setting screen

PV	
HHH	HH
	поп
011 012 01 01 01 01 01 01	E EE
PTN STEP	00
MENU < 🗸	ENT
МАРБА	SHIMAX

Initial Value: non

Setting range : Chosen from event type character table.

Being initialized if measuring range, scaling, and unit are changed.

function	Note	
No allotment		Default
Upper limit absolute value alarm	HR HR	
Lower limit absolute value alarm	128	
Within Absolute Value alarm	<u>_</u>	
Without Absolute Value alarm	<u></u>	
Scale over alarm	50	
Upper limit deviation value alarm	Нд	
Lower limit deviation value alarm	<u> </u>	
Within deviation alarm	Ēð	
Without deviation alarm	<u> </u>	
RUN signal	<i></i> Un	
CT1 Control loop alarm (heater braking)	ct 1_6	
CT1 Control loop alarm (loop)	ct /_L	
CT2 Control loop alarm (Heater braking)	c22_6	
CT2 Control loop alarm (loop)	c22_L	
3 phases Control loop alarm (Heaterbraking)	ct3_b	
3 phases Control loop alarm (loop)	ct3_L	
Step signal	SEP	
Pattern end signal	P_E	
Program end	End	
Step hold signal	Hold	
Program signal	ProC	
Up slope signal	U_SL	
Down slope signal	8_SL	
Guarantee signal	CuR	
Time signal 1	ES /	
Time signal 2	252	
Time signal 3	253	
Time signal 4	<u> </u>	

Event 1 differential-gap setting screen

Initial value : 5Digits





Setting range : 1~9999 Digits ON-OFF differential gap of event 1 is set Not displayed, when the event 1 mode are as follows. **non Sorum SEP P_E Hold Prof U_SL d_ SL GURES !~ 4** Being initialized if measuring range, scaling, and unit are changed.

Event 1 standby operation setting screen



Initial value : **OFF** Setting range : **OFF**, *i*, *Z* **OFF** : No standby operation, *i* : standby-operation only at the time of a poweron. *Z* : Standby-operation in the following cases. ;At the time of power-on. When each alarm's operating point is changed, When deviation alarm's SV is performed, When RUN/STBY (RST) is switched, When AUTO/MAN is switched. Not displayed, when the event 1 mode are as follows.

		MEP	IU
,			

non Sorun SEP P_ E Hold Pro GU_SL d_ SL GuRS I~4 Being initialized if measuring range, scaling, and unit are changed.

Event 1 latching setting screen



MENU

Initial value: **F** Setting range: **F** When latching is set as **G**, once event is output, even if event is OFF state event output state is held. Not displayed when event 1 mode is **G**, Being initialized if measuring range, scaling, and unit are changed.

Event 1 output characteristics setting screen



Initial value: no Setting range: no no: normal open nc: normal closing. Not displayed when event 1 mode is non Note: If nc is chosen, relay turns to ON about 1.5 seconds later when power source is switched on, and turns to OFF in event output range.

EV1 setting lead screen

6-6-7. Mode7 DO setting

Not displayed of Event 4 when option is not added. When CT or FB option is added, it is impossible to choose



DO mode setting screen



Initial Value: non Setting range : Chosen from Event type character table. Being initialized if measuring range, scaling, and unit are changed.





MENU

Initial Value:5 digit Setting range:1~9999digit ON-OFF differential gap of DO 1 is set Not displayed, when the event 1 mode are as follows. **non Sorum SEPP_E Hold Profile SL d_ SL**. **further** Start Being initialized if measuring range, scaling, and unit are changed.

Stand by operation settingscreen



Initial value : OFF Setting range : OFF、 1、2

 $_{\mathcal{O}}$ F F: No standby operation, : standby-operation only at the time of a poweron. $_{\mathcal{O}}$: Standby-operation in the following cases. ;At the time of power-on. When each alarm's operating point is changed, When deviation alarm's SV is performed, When RUN/STBY (RST) is switched, When AUTO/MAN is switched. Not displayed, when the event 1 mode are as follows.

MENU

non Sorun SEP P_ E Hold ProG U_ SL d_{-} SL GuRES I~4 Being initialized if measuring range, scaling, and unit are changed.

Latching release setting screen



Initial value: **F** Setting range: **FF , on**

When latching is set as **_n**, once DO is output, even if DO is OFF state event output state is held. Not displayed when DO 1 mode is **n_n**. Being initialized if measuring range, scaling, and unit are changed.







Initial value: no Setting range: no no: normal open nc: normal close Not displayed when DO 1 mode is non. Note: If nc is chosen, relay turns to ON about 1.5 seconds later when power source is switched on, and turns to OFF in DO output range. DO Output rating : Open collector Darlington output 24VDC (Max load 20mA), ON saturated voltage 1. 2V

Mode 7 lead screen

6-6-8. Mode8 DIsetting



Mode 8 screen is the setup screens of external control input (DI) option.

DI1 setting screen

PV	
HHH	H.H.
sv H H	ABA
	8.88
PTN STEP	00
WENU < 🗸	A ENT
MAPEA	SHIMAD

Initial Value:
____ Setting range: chosen from DI operation character table

Function		Input detection	Contents
No allotment	<u></u>		Default setting
SV selection SV1→ SV8	58 : ↓ 588	Level	Priority is given to younger number
SV3bit selection	58_36	Level	3 bits of continuation is occupied by the younger DI allotment
RUN	- U A	Level	RUN/STBY(RST)
PRG	ProC	Level	PRG/FIX
MAN	-A-	Level	MANUAL/AUTO
AT	RE	Edge	Auto tuning execution
PTN selection PTN1→ PTN8	P£n ; ↓ PEn8	Level	Priority is given to younger number
PTN 3bit selection	РълЗъ	Level	3 bits of continuation is occupied by the younger DI allotment
HOLD	Hold	Level	Program time stop
SKIP	SHEP	Edge	Shift to the following step of program,
Latching release	LS	Edge	All latching release
Super Key lock	LocY	Level	Fixed only to the basic screen key operation unacceptable
AI-SV/FIX-SV (V1.15~)	R <u>S_SL</u>	Level	Select AI–SV or FIX–SV for executing SV (Ramp&Soak function is disabled)

MENU

DI 2 ~DI7 are same as DI1



Initial Value: **ngn** Setting range: chosen from DI operation character table

Mode 8 lead screen

*When $5B : \sim 5BB$ are allotted to each DI, priority is given to younger No,.

*? can be performed at the time of a RUN-automatic output.

*When *R*^L is allotted to, release in the middle of AT operation is carried out by off-key operation chosen in AT screen.

*While AT is performed, if STBY (RST) or a manual output is performed, AT is released.

*Even when a keylock is not OFF, conducting of DI is effective.

*The same operation other than non is impossible to allot to DI1-DI7 at a time.

*Operation allotted to DI takes priority over DI.. Key operation cannot be performed.

*Execution of DI operation is possible to perform. But neither release of AT nor numerical change of SV and manual output is possible to perform.*In DI input, 5VDC 0.5mA per point is impressed. Use endurable switch, transistor and so on.

*Wiring distance of DI should be less than 30m.

*DI Input have to be needed at least 50msec signal to detect DI input .

*DI is non voltage contact or open collector. Rating: 5V DC 0.5mA/input

6-6-9. Mode9 AO setting



Not displayed when AO function is not installed





Initial value: non

Setting range: Chosen from event type character table. Data type allotted to analog output are chosen.

Function	Character
Non	
PV	PB
Execution SV	58
PV-SV Deviation	P8-58
Output 1	out /
Output2	0022
CT1	
CT2	c2
Servo position	Stofb

AO scaling lower limit value setting screen



Initial Value : Refer to the table below Setting range : Refer to the table below Not displayed when AO mode is Non

	MODE	Setting range	Initial value
PV SV	Sensor input	Within measuring range	Measuring range lower limit value
	Linear input	Within scaling range	Scaling range lower limit value
PV-SV Deviation		-50%~50%	-50%
Deviation,Out1, Out2, Servo position		0.0~100.0%	0.0%
CT1, CT	2	0.0~49.9A	0.0A
AO scaling upper limit value setting screen





Initial Value : Refer to the table below Setting range : Refer to the table below Not displayed when AO mode is Non

MODE		Setting range	Initial value
PV SV	Sensor input	Within measuring range	Measuring range upper limit value
	Linear input	Within scaling range	Scaling range upper limit value
PV-SV Deviation		-50%~50%	50%
Deviation,Out1, Out2, Servo position		0.1~100 %	100%
CT1, CT2		0.1~50.0A	50.0A

Analog output limiter lower limit value setting screen.



Initial value : 0.0%

Setting range : 0.0 ~ 100.0%

The lower limit value of analog output value (4–20mA or 0–10V) is set up by %. For example, output value of a lower limit value in each setup are : 8mA(25.0), 12mA(50.0), 16mA(75.0) and 20mA(100.0) respectively. Not displayed when AO mode is Non.

Analog output limiter upper limit value setting screen



Initial value : 0.0% Setting range : 0.0~100.0% The lower limit value of analog output value (4–20mA or 0–10V) is set up by %. For example, output value of a lower limit value in each setup are : 8mA(25.0), 12mA(50.0), 16mA(75.0) and 20mA(100.0) respectively. Not displayed when AO mode is Non If set as the same value as P_{L_1} and $P_{L_2}H$, it is fixed to the value. An analog output limiter can be made into reverse scaling. Example: Output range: 0°C (4mA) ~ 1200°C (20mA) can be 0°C (20mA) ~ 1200°C (4mA). Set AL_L as 100% and AL_H as 0%.

Rating : 4–20mA DC MAX load resistance 300 Ω 0–10V DC MAX load current 2mA

Mode 9 lead screen

6-6-10. Mode10 AI setting



Not displayed when AI function is not installed

AI operation mode setting screen

PTN STEP

MENU

ENT

Initial Value : Non Setting range : chosen from AI operation character table Function Character Non non 58 Executing SV 00 P8_oF MENU < 🗸 🖍 ENT PV offset correction out "L Out1 lower limit Out1 upper limit out IH <u>78</u>70 / Out1 manual operation point out2L Out2 lower limit out2X Out2 upper limit <u> 78-02</u> Out2 manual operation point E8 : Event 1 operatingpoint Event 2 operationg point *E83* Event 3 operatingpoint Event 4 operatingpoint *E8*4 do i DO1 operating point DO2 operating point do2 DO3 operating point do3 004 DO4 operating point doS DO5 operating point 005 DO6 operating point

No display when no option function or no function allotted below function:

006557.00654.68405.68 1~4.40 1~6

Execute SV value can be effected at FIX control, it can be set at program control but not effective.

Manual operation point can be effected at Manual control.

AI offset correction setting screen



Initial value : 0.0 Setting range : -5000~5000digit Offset can be corrected input signal.

AI gain correction setting screen



Initial value : 0.000Setting range: ± 5.000

Maximum input value is corrected within limit of $\pm 5.00\%$ of measuring range. If corrected, inclination of span changes in straight line which connects zero point and correction maximum value.



MENU

AI filter setting screen



Initial value : 0 Setting range : $0 \sim 10000$ sec When input change is violent or noise is overlapped, used in order to ease the influences.

In 0 second setting, filter does not function.

AI scaling lower limit setting screen



MENU

Initial value : 0 or lower limit of each range. Setting range : refer to the setting range table. Lower limit value of range allotted to analog input is set up An analog input limiter can be made into reverse scaling.

Function	Setting range
58	Within measuring range
P8_oF	-5000~5000
002 /L	0.0~ 100.0
out IX	0.0~ 100.0
	0.0~ 100.0
out2L	0.0~ 100.0
out2X	0.0~ 100.0
	0.0~ 100.0
E8 /~4	Belong to EV setting
do 1~6	Belong to DO setting

AI scaling upper limit setting screen



Initial value : 0 or upper limit of each range. Setting range : refer to the setting range table. Upper limit value of range allotted to analog input is set up An analog input limiter can be made into reverse scaling.

Mode 10 lead screen

6-6-11. Mode11 CT setting



Not displayed when CT function is not installed

CT1 mode setting screen



MENU

Initial value :

Setting range : **non.out i.out2.E8 i.E82.E83.E84** Object detected by CT (current) sensor is chosen. In the case of a current or voltage pulse output, **out i** is not displayed. **out 2** is not displayed without current output or output 2 option.





Initial value : 0.5

Setting range : $0.1 \sim 1000.0$ sec

When control loop abnormal alarm is allotted to event, delay time from switchover of operation (ON–OFF) to detection start is set up.

CT2 mode setting screen



Same as CT1 mode setting screen

CT2 delay time setting





Same as CT1 delay time setting

About control loop abnormal alarm

When the targeted output of a control loop abnormal alarm is ON, if current detected by CT is lower than the allotted event's operating point. (Setting Value of a basic screens, event operating point setting screen) alarm output is issued as breaking alarm.

When the targeted output is OFF, if detected current is higher than the allotted event's operating point(short-circuit, earth fault, etc.)

Mode 11 lead screen

6-6-12. Mode12 Communication setting screen

No display when communication function not installed Refer to Communication manual.

6-6-13. Mode13 Servo out setting screen

No display when Servo setting function not installed. Refer to Servo setting manual.

6-6-14. Mode14 PV SV multi points compensation setting screen

Mode 14 lead screen



This function is used for compensation Input value. More than 2 points of setting is needed to effective this function. Set point setting have to be needed bigger value than the previous value.

Operation mode settingscreen









MENU

Initial Value: **C** Setting range: **L C n E R** -5.00~105.00 % **P B B W** within measuring range(scaling) **S B B W** within measuring range(scaling) **R C S B** within measuring range(scaling)

Set point 1 value setting screen

PV	Initial Value: 🛄
RAHAA	Setting range: とこっとЯ -5.00~105.00 %
sv	PB_PB ±10000 digit
	58_78 ±10000 digit
PTN STEP 00	R58 ±10000 digit
MENU < 🖂 🏠 ENT	Decimal point of PB_PB , 5B_PB and RE_5B are depend on
MAP6A SHIMAX	measuring range.

Set point 2 position setting \sim Set point 11 position setting are same as 1 Set point 2 value setting \sim Set point 11 value setting are same as 1

7. Supplementary Explanation of Function

7-1. Auto return function

When there is no key operation 3 minutes or more, on the screen except for basic screen and each monitoring screen, screen automatically shifts to basic screen.

7-2. Output soft start function

This is the function to increase the control output gradually with set-up time at the time of power-on,

STBY \rightarrow RUN, and normal return from scale over.

This is effective for controlling the excessive current to loads, such as a heater.

Soft start functions in the following conditions.

•At the time of the power–on in automatic operation, STBY (RST) \rightarrow RUN, and normal return from scale over.

• Setup of proportional band (P) is other than OFF

• Soft starting time is not OFF

7-3. Event selection alarm operation figure





7-4. AT (Auto Tuning)

• If AT is performed by FIX (constant value control), AT monitor LED blinks and light is put out by termination or intermediate release.

•When auto tuning is ended in inclination step or chosen all PID(s), it is in standby state until one pattern is completed. Then lights up, then puts out when one pattern is completed.

When AT is not completed within 1 pattern, AT conducting is released when one pattern is completed.

• Even in inclination step, AT is performed if it is in HOLD state.

AT at the time of 2 output specification is as follows.

At the time of heating / cooling operation and cooling / heating operation = OUT1, OUT2 common – PID value At the time of heating / heating operation and cooling / cooling operation, only OUT1 performs AT. OUT 2 output while performing AT is 0% or output limiter lower limit value.

8. Trouble Shooting

Contents of defects	Cause	Treatment
Error message display	Refer to cause and treatment of error display	Refer to cause and treatment of error display
PV display is not normal	Mismatch of instrument and input. Fault in the wiring.	Type code, check of specification. Check of wiring.
Display disappeared and does not operate	Power is not supplied. Abnormality of instrument.	Check of a power supply (voltage of terminal, switch, fuse, wiring).
Key operation impossible	Keylocked. Abnormality of instrument.	Release of keylock. Check of instrument, repair, exchange.

8-1. Cause and treatment of main defects

8-2. Cause and treatment of error display

Error display	Contents	Cause	Treatment
НННН)	Scale over in upperlimit	 wire breaking of thermocouple input wire breaking of resistance bulb input A when input exceeds upper limit of measuring range by 10% 	1.wire breaking check of thermocouple input wiring, replacement of thermocouple 2.check of resistance bulb A wiring, replacement of resistance bulb 3.check of input voltage value and current value, input transmitter and specification (matching of incoming signal and meter specification)
LLLLL (LLLLL)	Scale over in lowerlimit	1.when input exceeds lower limit of measuring range by 10% 2.wire breaking of resistance bulb input B	1.polarity of input is reverse, check of wiring and an input transmitter 2.check of resistance bulb B wiring, replacement of resistance bulb
	Breaking of resistance bulb input	1.wire breaking of b	1.check of resistance bulb wiring
b (b)		2.multiple wire breaking combinations in ABb (A and B, A and b, B and b, all of ABb)	2.replacement of resistance bulb
С]_НН (СЈ <u></u> НН)	Cold junction (CJ) temperature of thermocouple input is scale over in upper limit side	When ambient temperature of a meter exceeds 80°C	 make Ambient temperature of meter within use environment condition temperature Check the meter when ambient temperature is not over 80°C
<i>E J_LL</i> (CJ_LL)	Cold junction (CJ) temperature of thermocouple input is scale over in lower limit side	When ambient temperature of meter becomes less than −20°C	 Make ambient temperature of meter within use environment condition temperature Check the meter when ambient temperature is not less than -20°C

9. General specification

Display

(1)Display method				
Digital display	PV red 7segment LED 5 digits (height of the character 20mm) SV green 7segment LED 5Digits (height of the character 13mm)			
	PTN/SV–No, gre	en 7segment LED 1digit (height of the character 10mm)		
	STEP/PID-No. g	reen 7segment LED 2digit (height of the character10mm)		
Bar graph display	20dots green LE	D		
	Non allotment, deviation, OUT1, OUT2			
	Servo valve posit	ion (Servo)		
	STEP time rate,	PTN step rate, number of executions rate (Program)		
Status display		green FD		
	EV1~4	Yellow LED		
	AT	green LED		
	RUN	green LED (blinking at MANUAL)		
	PRG	green LED (Program)		
	DO1~6	vellow LED		
	GUA	green LED (Program)		
	HLD	green LED (Program)		
	(Up)	yellow LED (Program)		
	(Flat)	yellow LED (Program)		
	(Down)	yellow LED (Program)		
(2)Display accuracy	TC $\pm (0.1)$	%FS+1digit)CJ error not include		
	RTD $\pm (0.1)$	%FS+0.1deg)		
	Others $\pm (0.1)$	%FS+1digit)		
(3) Accuracy maintenance range	23°C±5°C			
(4) Accuracy stability	\pm 0.04%FS (90da)	ys_23°C), ±0.06%FS (1year 23°C)		
(5)Display resolution	belong to measur	ing range and scaling (0.0001/0.001/0.01/0.1/1)		
(6)Display range	Within PV limiter (-10% \sim 110% of measuring range)			
	💥 Lower limit of	display is −270°C		
	⅔ Lower limit of	measuring range is −240°C at P1, JP1, P2, and JP2		
(7)Display renewal period	Same as samplin	g period(50, 166.7, 250, 500 msec)		
(8)Input scaling	Possible at current input and voltage input (-20000 \sim 32000 span10 \sim 50000)			
(9)Decimal point	Non, 1/10, 1/100, 1/1000, 1/10000			

Setting

(1) Setting method

(2) Number of SV setting

(3) SV setting range

(4) Key lock

MAC6A By 6 front keys (RM RM 🗨 💌 🛦 RM) MAP6A By 8 front keys (RUN MEN () MAP6A By 8 front keys (RUN MEN () MAX 8 points Same as measuring range (within SV limiter) OFF, 1~6 (7 levels)

	Operation	Level	Contents	
		OFF	No lock	
		1	Settings of Mode1-14 screens are not changeable. (key operation acceptable)	
		2	Execution SV, manual numerical, key lock level, settings of basic screens, step settings in program setting screens are possible. (RM key operation acceptable)	
	Key setting	3	Execution SV and a manual numerical change are possible. And change of a key lock level is possible. (RM key operation acceptable)	
		4	Possible to change numerical value manually and key lock level. (RM key operation acceptable)	
		5	Possible to change key lock level. (hunkey operation acceptable)	
		6	Possible to change key lock level. (PM key operation unacceptable)	
	DI setting		Shift between screens prohibited. Fixed only to the basic screen.	
(5) PV limiter	Within measu	ring range (Lo <hi)< td=""></hi)<>	
	Over scale(H	HHHH) or u	nder scale(LLLLL) is displayed at outside measuring range	
(6) SV limiter	Upper limit an	d Lower lim	nit can be set individually within measuring range	
	(Lower limit <l< td=""><td>Jpper limit a</td><td>and within PV limit)</td></l<>	Jpper limit a	and within PV limit)	
(7) Unit setting	°C(Centigrade	e) °F(Fahre	nheit) K(Kelvin)	
(8) PV-SV characteristics correction	$11point \pm 10$	000dig Inpl	ıt.	
(9) Input	Full multi (TC, Pt, mV, V, mA)			
Thermo couple				
Input resistance	500kΩ or more			
External resistance tolerance	100Ω or less			
Inferences of lead wire	1.2μ V/10Ω			
Burn out	Standard equipment up scale only			
Compensation accuracy of reference	Within accuracy maintenance \pm 1°C (Ambient temperature 5~45°C \pm 2°C)			
junction				
Reference junction mode	Selected betw	veen interna	al and external.	
	*1 ±0.5%FS	(PV value a	at -100 to 0°C)	
	*2 $\pm 0.7\%$ FS (PV value at -100°C or less)			
	*3 Accuracy	s not guara	nteed below B:400°C(752°F)	
Resistance bulb				
Stipulated current	About 1mA			
Resistance latitude of lead wire	5Ω or less (e	equivalent ir	n the resistance value of 3 lines)	
Inferences of lead wire resistance	Max0.3%FS at	:10Ω orm	nore by each lead wire	
	Max0.7%FS at	: 20Ω or m	nore by each lead wire	
Voltage	Input resistance : 500k Ω or more			
Current	Reception res	istance : 10	0Ω (External resistance needed 0.05% 25ppm/°C)	
(10) Sampling period	50, 166.7, 250	, 500ms		
(11) PV filter	0~10000sec			
(12) PV off set	± 5000 unit			
(13) PV gain	$\pm 5.000\%$			
(14) Characteristics correction	①Linearity correction : 11point \pm 10000digit			
②PV-PV Characteristics correction : 11point ±10000digit			ics correction : 11point \pm 10000digit	

Measuring range

Thermocouple			
Character	°C Centigrade	°F Fahrenheit	K Kelvin
- i	-50.0 ~ 1760.0	-50.0 ~ 3200.0	220.0 ~ 2030.0
P:	-270.0 ~ 1370.0	-450.0 ~ 2500.0	0.0 ~ 1640.0
<i>24</i>	0.0 ~ 800.0	0.0 ~ 1500.0	270.0 ~ 1070.0
<i>2</i> 4	-200.0 ~ 400.0	-300. 0 ~ 700. 0	70.0 ~ 670.0
РЧ	0.0 ~ 300.0	0.0 ~ 600.0	270.0 ~ 570.0
11	-200. 0 ~ 1200. 0	-320. 0 ~ 2200. 0	70.0 ~ 1470.0
55	0.0 ~ 600.0	0.0 ~ 1100.0	270.0 ~ 870.0
と /	-270.0 ~ 400.0	-450. 0 ~ 700. 0	0. 0 ~ 670. 0
E :	-270.0 ~ 1000.0	-450. 0 ~ 1800. 0	0. 0 ~ 1270. 0
5:	-50.0 ~ 1760.0	-50.0 ~ 3200.0	220. 0 ~ 2030. 0
U 1	-200. 0 ~ 400. 0	-300. 0 ~ 700. 0	70.0 ~ 670.0
n 1	-270.0 ~ 1300.0	-450. 0 ~ 2300. 0	0. 0 ~ 1570. 0
51	0. 0 ~ 1820. 0	0 ~ 3300	270. 0 ~ 2090. 0
5-26	0. 0 ~ 2320. 0	0 ~ 4200	270.0 ~ 2590.0
PL2	0. 0 ~ 1390. 0	0. 0 ~ 2500. 0	270.0 ~ 1660.0
RTD			
P :	-200. 0 ~ 850. 0	−300. 0 ~ 1500. 0	70.0 ~ 1120.0
<i>P2</i>	-200.00 ~ 300.00	-300.0 ~ 600.0	70.00 ~ 570.0
P3	-100.00 ~ 300.00	-150.0 ~ 600.0	170.0 ~ 570.0
рч	-100.00 ~ 200.00	-150.0 ~ 400.0	170.0 ~ 470.0
PS	-100.00 ~ 100.00	−150.00 ~ 200.00	170.0 ~ 370.0
P6	0. 00 ~ 200. 00	0.0 ~ 400.0	270.0 ~ 470.0
PJ	0. 00 ~ 100. 00	0.00 ~ 200.00	270 . 0 ~ 370. 0
P8	-50.00 ~ 50.00	-60.00 ~ 120.00	220.00 ~ 320.00
P9	-20. 000 ~ 30. 000	0.00 ~ 100.00	250.00 ~ 300.00
JP (-200.0 ~ 500.0	-300.0 ~ 900.0	70.0 ~ 770.0
765	$-20.000 \sim 300.00$	-300.0 ~ 600.0	70.00 ~ 570.0
<u></u>	-100.00 ~ 300.00	-150.0 ~ 600.0	170.0 ~ 570.0
	-100.00 ~ 200.00	-150.0 ~ 400.0	170.0 ~ 470.0
JPS	-100.00 ~ 100.00	-150.00 ~ 200.00	170.00 ~ 370.0
JP5	0.00 ~ 200.00	0.0 ~ 400.0	270.0 ~ 470.0
ויקנ	0.00 ~ 100.00	0.00 ~ 200.00	270.0 ~ 370.0
<u></u>	-50.00 ~ 50.00	-60.00 ~ 120.00	220.0 ~ 320.00
<u></u>	$-20.000 \sim 30.000$	0.00 ~ 100.00	250.00 ~ 300.00
Linerinput			
<u> </u>	-100 ~ 100		
<u>~</u>	0 ~ 100		
<u>nd</u>	0 ~ 50		
<u> </u>	10 ~ 50		
	$0 \sim 20$	Scaling	
<u></u>	$-10 \sim 10$	-20000~32000	
<u> </u>	0 ~ 10	Span	
8:	$-10 \sim 10$	10~50000 or less	
	$0 \sim 10$		
83	$0 \sim 5$	Decimal point	
87		Non 0. 1~0. 0001	
	0 ~ 2		
00	$-1 \sim 1$		
	$0 \sim 20$		
<u> </u>	4 ~ 20		

Control

(1) Control method (2) Number of PID (3) Number of Zone (4) Zone hysteresis (5) Proportional band (P) (6) ON-OFF Differential gap(H) (7) ON-OFF Differential gap(L) (8) Integration time(I) (9) Differential time(D) (10) Manual reset (11) Dead band (12) Output limiter (13) Soft start (14) Control output characteristic (15) Proportional period (16) Output renewal period (17) Manual output (18) FlexPID setting method (ABC)

Control Output 1

(1) Contact
 (2) Voltage pulse(SSR drive)
 (3) Current
 (4) Voltage
 (5) Contact(Servo)
 (6) SSR(Servo)
 (7) Accuracy
 (8) Resolution

Control Output 2

(1)~(4)
(5)~(6)
(7)

2mode PID method with Auto tuning +Zone PID method or ON-OFF operation Max 8 Max 4 0~10000 units OFF ,0.1~1000.0 FS (On - Off operation by OFF setting) 1~10000 Units 1~10000 Units OFF ,1~6000s (P or OD operation by OFF setting) OFF ,1~3600s (P or PI operation by OFF setting) \pm 50.0%(Effective at I=OFF) -20000~30000 Units (L) 0.0~99.9% (H)0.1~100.0% (resolution 0.1) OFF, 0.1~300.0s (resolution 0.1) Possible to choose from RA(Heating) or DA(Cooling) 0.5~300.0s (resolution 0.5) Same as sampling period (50,166.7,250,500m sec) 0.0~100.0% (resolution 0.1) 0.00~1.00

Normal open (1a) 240V AC 2A(resistance load) 12VDC $-1 \sim \pm 1.5 V$ (Max 20mA) 4-20mA(load resistance 500 Ω) Load regulation 0. 2%FS 0-10V(Max load 2mA) Normal open (2a) 240V AC 2A 2 circuits of Triode AC switch 240V AC 1.5A $\pm 1.0\%$ FS(5 \sim 100% Output) About 1 \checkmark 50000

Same as Control Output 1 (Exclusive selection option of Servo output) No function Resolution:About 1/50000

Event Output(EV1~3)(Option)

(1)Output rating (2)Operation

(3) Differential gap

(4) Types of Event

Normal open (1a \times 3points) 240V AC 1A(resistance load) ON–OFF operation 1~10000 unit (At alarmfunction) EV1 , EV2 and EV3

Function		Note
No allotment	000	Default
Upper limit absolute value alarm	HR -	
Lower limit absolute value alarm	18	
Within Absolute Value alarm	[<i>こ</i> 8	
Without Absolute Value alarm	<u>o</u> 8	
Scale over alarm	50	
Upper limit deviation value alarm	Нd	
Lower limit deviation value alarm	<u> </u>	
Within deviation alarm	<u>īd</u>	
Without deviation alarm	<u> </u>	
RUN signal	run	
CT1 Control loop alarm (heater braking)	ct 1_6	
CT1 Control loop alarm(loop)	ct 1_L	
CT2 Control loop alarm (Heater braking)	ct2_b	
CT2 Control loop alarm (loop)	ct2_L	
3 phases Control loop alarm (Heater braking)	ct3_b	
3 phases Control loop alarm (loop)	ct3_L	
Step signal	SEP	
Pattern end signal	P_E	
Program end	End	
Step hold signal	Hold	
Program signal	ProG	
Up slope signal	U_56	
Down slope signal	d_SL	
Guarantee signal	5 <i>.</i>	
Time signal 1	ES (
Time signal 2	223	
Time signal 3	E53	
Time signal 4	254	

(5) Setting range

Upper limit absolute alarm ,Lower limit absolute alarm : Within measuring range Deviation alarm : Upper limit -20000~30000, Lower limit -20000~30000 Unit Without deviation : 0~30000 Unit

Without	deviation	: 0~30000 Unit
Within de	viation	:0~30000 Unit
Control le	оор	: 0.0~50.0A

OFF No standby operation 1 Only at the time of Power on, stand by operation 2 At the time of Power On+Execution SV, RUN/STBY, AUTO/MAN, andEV are changed.

(7) Output characteristic

(6) Stand by operation

:Normal open(,,), Normal close(,)

Available

% If $\frown {\it C}$ is chosen and power is turn on, relay become On about 1.5s and become off.

(8) Latching

(9) Latching release	Release is done by key operation ,DI or power OFF, In case of release by DI and power OFF all the alarm are called off simultaneously
(10) Output renewal period	50,166.7,250,500m sec
Event Output 4(EV4)(Option)	
(1) Output rating	Normal open (1a) 240V AC 2A(resistance load)
(2)~(9)	Same as EV1~3
(10) Additional condition	Exclusive selection option of Servo Output2

External operation input (DI) Option

(1) Number of input
 (2) Input detections

7points Edge and Level

Function		Input detection	Contents
No allotment	поп		Default setting
SV selection SV1→SV8	58 : ↓ 588	Level	Priority is given to younger number
SV 3bit selection	58_36	Level	Priority is given to younger number
RUN	run	Level	RUN/STBY(RST)
PRG	ProC	Level	PRG/FIX
MAN	<u> 780</u>	Level	MANUAL/AUTO
AT	RE	Edge	Auto tuning execution
PTN selection PTN1→PTN8	PEn ; ↓ PEn8	Level	Priority is given to younger number
PTN 3bit selection	PEn36	Level	3 bits of continuation is occupied by the younger DI allotment
HOLD	Hold	Level	Program time stop
SKIP	SHEP	Edge	Shift to the following step of program,
Latching release	L_rS	Edge	All latching release
Super Key lock	LocY	Level	Fixed only to the basic screen key operation unacceptable

(3) Input rating

Voltage 5V DC(0.5mA/1 input)

Min 50msec

(4) Input signal time(5) Operation input

Dry contact or Open collector (min 50msec)

External operation output(DO)(Option)

(1) Number of output

6 points

(2) Types of Output	Same as EV1~3
(3) Output rating	Open collector Darlington output 24VDC (Max load 20mA), ON saturated voltage1.2V
(4) Output renewal time	Same as sampling period (50,166.7, 250, 500m sec)
(5) Installation condition	DO4 \sim 6 Exclusive selection option of Feedback input and CT input

Program function (option)

(1) Number of pattern

- (2) Number of steps
- (3) Time setting
- (4) Time setup resolution (5) Time accuracy (6) Step setting parameter (7) Step signal (8) Pattern end signal (9) Program END (10) Time signal (11) Pattern execution number: (12) PV start (13) Guarantee soak (14) Hold (15) Skip (16) Power failure compensation

Communication function (option)

(1) Communication port

(2) Communication method

(3) Synchronization method

(4) Communications distance

(5) Communication speed

- (6) Data format
- (7) Master mode
- (8) Slave address 1~255 (9) Parameter preservation mode Choose from RAM, MIX and EEP mode. (10) Error detection None, Choose from ADD, complement of ADD +2, exclusive OR, CRC-16 and LRC None 1~500ms (resolution1ms) ASCII code or binarycode SHIMAX Standard or MODBUS ACII, MODBUS RTU protocol When P10 or JP10 chosen the data width with a parameter beyond 16bit, only to 1 digit of decimal point below.

cascade control.

1ch

RS-232C/1set, RS-485/Maximum 256 sets (depends on conditions, host is included) RS-232C/Non need, RS-485/120Ω (External connection)

0.0 hour \sim 3200.0 hours or ∞ (by each steps) 0 hour 0 minutes ~ 300 hours 59 minutes or ∞ (by each steps) 0 minutes 0 second \sim 300 minutes 59 seconds or ∞ (by each steps) 0.1 hour or 1 second \pm (setting time \times 0.02% + 0.1 second) SV, step time, PID No, Independent EV At step to next step $-1000.0 \sim 1000.0$ s (setting resolution 0.5s) At pattern end $-1000.0 \sim 1000.0$ s (setting resolution 0.5s) At program end $-1000.0 \sim 1000.0$ s (setting resolution 0.5s) By each 1step (possible to set ON or OFF) Max 30000 or ∞ ON/OFF OFF, 1~9999 units Possible by front key, DI allotment or communication Possible by front key, DI allotment or communication

Max 8 (1, 2, 3, 4, 6, 8 patterns) 12~96 (Total steps = 96)

ON/OFF (Step time which is at power failure is not guaranteed)

RS-485 : 2 line system half-duplex multi-drop (bus) system

RS-232C : Max15m, RS-485 : Max 500m (depend on a condition)

Start1 Stop1.2 Data 7.8bit Non parity odd number, even number

Possible to chosen from SV, OUT1, OUT2(1:n Number of slave max 255) When MAC6 is a master, slave address range must be continuation. XWhen MAC6 is a master, bus connection with other host PCs is not allowed. XInput range of master machine and slave machine should be equal, at the time of

RS-232C : 3 line system half-duplex system

The start stop synchronization system

1200, 2400, 4800, 9600, 19200, 38400 bps

- (11) Flow control
- (12) Delay
- (13) Communication code
- (14) Protocol
- (15) Other condition
- (16) Number of connection
- (17) Termination resistance

External analogue input (AI) (option) /**/**/

1ch
Execution SV, EV1~4, DO 1~6 level, OUT1~2 Upper and lower limiter,
PV Off set、Manual output
4–20mA (Reception resistance100 Ω)
0–10V (Input resistance about 500k Ω)
±0.1%FS
0.2, 0.667, 1, 2 sec
–20000 \sim 30000 reserve scaling permitted (within a setting range)
0~10000 sec
±5000 unit
±5.000 %
11point \pm 32000 digit

External analogue output (AO) (option) (1) Number of output 1ch

(I) Number of output	ICh
(2) Allotment function	PV、Execution SV、OUT1、OUT2、CT1、CT2、DEV
(3) Current	4–20mA DC (Max load 300 Ω) load regulation \pm 0.05%FS
(4) Voltage	0–10V DC (Max load 2mA)
(5) Output accuracy	$\pm 0.1\%$ FS ($\pm 0.2\%$ FS at PV output)
(6) Scaling	Within measuring range or output range
(7) Limiter	0.0~100.0 % (reserve setting permitted)
(8) Output resolution	About 1/50000
(9) Output renewal period	50, 166.7, 250, 500 msec

Current sensor input (CT1, 2) (option)

(1) Number of input	2ch
(2) Detection method	Current judging system by CT sensor
(3) Detection range	0.0~55.0A
(4) Sampling period	100m sec
(5) Detection accuracy	±3%fs
(6) Detection delay time	0.1~1000.0 sec (resolution 0.1sec)
(7) Alarm output	Assigned to event
(8) Detection object	Assigned to OUT1, OUT2, EV1, EV2, EV3, EV4
(9) Setting range	0.0~50.0A (Default 0.0)
(10) Recommended CT sensors	U_RD co., CTL-6-L CTL-6-V CTL-6-P-H CTL-6-S-H CTL-12L-8
(11) Other condition	Exclusive selection option of Feedback input

Feedback input (FB) (Servo controloption)

(1) Potentiometer rating	Any between 100 Ω and 2k $\Omega/$ three–wire type
(2) Input accuracy	\pm 1%FS
(3) Sampling period	100m sec
(4) Zero span adjustment	Manual and Auto
(5) FB filter	0~10000 sec

Infrared-ray communication

(1) Communication method	Infrared link system
(2) Synchronous system	Start stop synchronization system
(3) Communication speed	9600bps
(4) Data format	start 1 stop 1 Data 8bit non parity
(5) Slave address	1
(6) Parameter preservation mode	EEP
(7) Error detection	CRC-16
(8) Communication code	binary code
(9) Protocol	MODBUS-RTU

General specifications

(1) Data save	By nonvolatile memory (EEPROM)
(2) Temporary dead time	No influence within 0.05 second 100% dip
(3) Use environmental condition	Temperature∕−10~55°C
	Humidity/Below 90% RH (no dew condensation)
	Height/ Altitude of 2000m or less
	Category/ II
	Contamination degree/2
(4) Storage temperature Conditions	−20~65°C
(5) Power supply	100~240V (90~264V) AC 50/60Hz
(6) Input noise removal ratio	Normal 50dB or higher
(7) Impulse-proof noise	Power-source Normal 100ns/1µ s±1500V
(8) Insulation resistance	Between input/output terminal and power supply terminal 500V DC 20 Ω or higher
	Between input/output terminal and earth 500V DC $20M\Omega$ or more
(9) Withstand voltage	Between input/output terminal and power supply 2300V AC 1minute
	:Output and earth 1500V AC 1 minute(Output and others500V)
	Power supply and earth 1500V AC 1 minute
	Input and earth 500V AC 1 minute
	Input and output 500V AC 1 minute (Input and output(contact)2300V)
(10) Resistance to vibration	Frequency10 \sim 55 \sim 10Hz, amplitude 0.75mm (one side amplitude)…100m/S ²
	Direction 3 directions
	Sweep speed 1 octave/minute (about 5 minutes for both-way/cycle) Number of sweep
	10 times
(11) Power consumption	12VA
(12) Applicable standard	EMC EN61326-1
	Safety IEC/EN61010-1
	Oscillation IEC60068-2-6
(13) Case material/color	PPO PPE /Light gray (Mansel value 3.73B7.77/0.25)
(14) Outside dimension	H96 × W96 × D69mm(depth in panel 65mm)
(15) Thickness of applied panel	1.2 \sim 3.2mm(Mounting is possible up to 20mm with mounting bracket)
(16) Size of attachment hole	H92 × W92mm
(17) Group mounting	Group mounting is possible of horizontal direction
	XAttachment is needed of dismounting vertical plural mounting
(18) Weight	About 300g

Isolation block chart



No insulation

Functional insulation Basic insulation



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